

## Academic Course Description

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| <p><b>BHARATH UNIVERSITY</b><br/> Faculty of Engineering and Technology<br/> Department of Electrical and Electronics Engineering<br/> <b>BEE052 &amp; ELECTRICAL MACHINE MODELING AND ANALYSIS</b><br/> <b>Sixth Semester (Even Semester)</b></p> |
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### Course (catalog) description

To master the various fundamentals, machine design, machine modeling of various types of electrical machines. This will help you to gain knowledge and to do research in the area of electrical machine modeling

**Compulsory/Elective course:** Elective for EEE students

Credit & Contact hours : 3 and 45 hours

Course Coordinator : Mrs.Anitha Sampath kumar

**Instructors** : S. Dinakar Raj

| Name of the instructor | Class handling    | Office location | Office phone | Email (domain:@bharathuniv.ac.in) | Consultation |
|------------------------|-------------------|-----------------|--------------|-----------------------------------|--------------|
| S. Dinakar Raj         | Third year<br>EEE | KS 302          | 04422290125  | rajdina@gmail.com                 | 9.00-9.50 AM |

### Relationship to other courses:

Pre-requisites : BEE504 (Electrical Machine Design)

Assumed knowledge : Knowledge in machine design

### Syllabus Contents

#### UNIT I BASIC CONCEPTS OF MODELING

9

Basic Two - pole Machine representation of Commutator machines, 3 phase synchronous machine with and without damper bars and 3 - phase induction machine, Kron's primitive Machine - voltage, current and Torque equations. DC Machine modeling: Mathematical model of separately excited D.C motor -Steady State analysis - Transient State analysis - Sudden application of Inertia Load - Transfer function of Separately excited D.C Motor - Mathematical model of D.C Series motor, Shunt motor - Linearization Techniques for small perturbations

#### UNIT II REFERENCE FRAME THEORY

9

Reference frame theory Real time model of a two phase induction machine-Transformation to obtain constant matrices - three phase to two phase transformation - Power equivalence. Dynamic modeling of three phase Induction Machine Generalized model in arbitrary reference frame - Electromagnetic torque -

Derivation of commonly used Induction machine models - Stator reference frame model - Rotor reference frame model Synchronously rotating reference frame model -Equations in flux linkages - per unit model

### UNIT III SMALL SIGNAL MODELING

9

Small Signal Modeling of Three Phase Induction Machine Small signal equations of Induction machine – derivation - DQ flux linkage model derivation - control principle of Induction machine. Symmetrical and Unsymmetrical 2 phase Induction Machine Analysis of symmetrical 2 phase induction machine - voltage and torque equations for unsymmetrical 2 phase induction machine - voltage and torque equations in stationary reference frame variables for unsymmetrical 2 phase induction machine - analysis of steady state operation of unsymmetrical 2 phase induction machine - single phase induction motor - Cross field theory of single - phase induction machine.

### UNIT IV MODELING OF SYNCHRONOUS MACHINE

9

Synchronous machine inductances – voltage equations in the rotor’s dq0 reference frame - electromagnetic torque - current in terms of flux linkages - simulation of three phase synchronous machine- modeling of PM Synchronous motor.

### UNIT V DYNAMIC ANALYSIS OF SYNCHRONOUS MACHINE

9

Dynamic performance of synchronous machine, three -phase fault, comparison of actual and approximate transient torque characteristics, Equal area criteria

#### Text Books:

- T1. R. Krishnan, “Electric Motor Drives - Modeling, Analysis& control”, Pearson Publications, First edition, 2002.  
T2. P.C.Krause, Oleg Wasynczuk, Scott D.Sudhoff, “Analysis of Electrical Machinery and Drive systems”, IEEE Press, Second Edition

#### References:

- R1.P.S.Bimbra, “Generalized Theory of Electrical Machines” Khanna publications, Fifth edition - 1995  
R2. CheeMunOng –“Dynamic simulation of Electric machinery using MATLAB / Simulink”, Prentice Hall of India Publications  
R3. Online courses on Modeling of Electrical Machines -<http://nptel.ac.in/courses/108106023/>

#### Computer usage:

#### Professional component

|                                       |   |      |
|---------------------------------------|---|------|
| General                               | - | 0%   |
| Basic Sciences                        | - | 0%   |
| Engineering sciences & Technical arts | - | 0%   |
| Professional subject                  | - | 0%   |
| Major Elective                        | - | 100% |

**Broad area :** Electrical Machines/Electronics/Power system/Control &Instrumentation.

## Test Schedule

| S. No. | Test                   | Tentative Date                | Portions             | Duration  |
|--------|------------------------|-------------------------------|----------------------|-----------|
| 1      | Cycle Test-1           | February 2 <sup>nd</sup> week | Session 1 to 14      | 2 Periods |
| 2      | Cycle Test-2           | March 2 <sup>nd</sup> week    | Session 15 to 28     | 2 Periods |
| 3      | Model Test             | April 3 <sup>rd</sup> week    | Session 1 to 45      | 3 Hrs     |
| 4      | University Examination | TBA                           | All sessions / Units | 3 Hrs.    |

## Mapping of Instructional Objectives with Program Outcome

| To master the various fundamentals, machine design, machine modeling of various types of electrical machines. This will help you to gain knowledge and to do research in the area of electrical machine modeling | Correlates to program outcome |                 |      |
|--|-------------------------------|-----------------|------|
|  | H                             | M               | L    |
| 1. To learn about the basic concepts of AC/ DC machine modeling.   | b                             | c,d,e,f,g,i,j,l | h, k |
| 2. To study about the dynamic modeling and phase transformation  | b,e                           | d,f,g,i,j,l     | h,k  |
| 3. To analyze various methodologies in small signal machine modeling   | a,b                           | i,j             |      |
| 4. To understand the modeling of synchronous machine modeling  | a,f,l                         | c,g,j           |      |
| 5. To learn the performance and dynamic modeling of synchronous machines   | a,b,d,e,f                     | c,g,h,i,j,l     | l    |

H: high correlation, M: medium correlation, L: low correlation

Draft Lecture Schedule

| S.NO                                     | Topics  | Problem solving (Yes/No) | Text / Chapter |
|--|---|--------------------------|----------------|
| <b>UNIT I BASIC CONCEPTS OF MODELING</b> |   |                          |                |
| 1.                                       | Basic Two - pole Machine representation of Commutator machines  | NO                       | [R1],[T1]      |
| 2.                                       | 3 phase synchronous machine with and without damper bars  | NO                       |                |
| 3.                                       | 3 - phase induction machine   | YES                      |                |
| 4.                                       | Kron's primitive Machine - voltage  | YES                      |                |
| 5.                                       | current and Torque equations  | YES                      |                |
| 6.                                       | DC Machine modeling   | YES                      |                |
| 7.                                       | Transient State analysis  | YES                      |                |
| 8.                                       | Sudden application of Inertia Load b  | YES                      |                |
| 9.                                       | Transfer function of Separately excited D.C Motor   | YES                      |                |
| 10.                                      | Mathematical model of D.C Series motor, Shunt motor   | YES                      |                |
| 11.                                      | Linearization Techniques for small perturbations  | YES                      |                |
| <b>UNIT II REFERENCE FRAME THEORY</b>    |   |                          |                |
| 12.                                      | Reference frame theory Real time model of a two phase induction machine   | YES                      | [R1],[T2]      |
| 13.                                      | Transformation to obtain constant matrices  | YES                      |                |
| 14.                                      | three phase to two phase transformation   | YES                      |                |
| 15.                                      | Power equivalence. Dynamic modeling of three phase Induction Machine Generalized model in arbitrary reference frame | YES                      |                |
| 16.                                      | Electromagnetic torque  | YES                      |                |
| 17.                                      | Derivation of commonly used Induction machine models  | YES                      |                |
| 18.                                      | Stator reference frame model  | YES                      |                |
| 19.                                      | - Rotor reference frame model Synchronously rotating reference frame model  | YES                      |                |
| 20.                                      | Equations in flux linkages  | YES                      |                |

|   |  |     |                |
|---|--|-----|----------------|
| 21.   | per unit model   | YES |                |
| <b>UNIT III SMALL SIGNAL MODELING</b>                 |  |     |                |
| 22.   | Small Signal Modeling of Three Phase Induction Machine<br>Small signal equations of Induction machine            | YES | [R1],[T1]      |
| 23.   | derivation - DQ flux linkage model derivation - control principle of Induction machine                           | YES |                |
| 24.   | Symmetrical and Unsymmetrical 2 phase Induction Machine Analysis of symmetrical 2 phase induction machine        | YES |                |
| 25.   | voltage and torque equations for unsymmetrical 2 phase induction machine   | YES |                |
| 26.   | voltage and torque equations in stationary reference frame variables for unsymmetrical 2 phase induction machine | YES |                |
| 27.   | analysis of steady state operation of unsymmetrical 2 phase induction machine                                    | YES |                |
| 28.   | single phase induction motor   | YES |                |
| 29.   | Cross field theory of single   | YES |                |
| 30.   | phase induction machine  | YES |                |
| 31.   | Problem solved   | YES |                |
| <b>UNIT IV MODELING OF SYNCHRONOUS MACHINE</b>        |  |     |                |
| 32.   | Synchronous machine inductances  | YES | [R1],[T1],[R3] |
| 33.   | voltage equations in the rotor's dq0 reference frame   | YES |                |
| 34.   | electromagnetic torque   | YES |                |
| 35.   | current in terms of flux linkages  | YES |                |
| 36.   | simulation of three phase synchronous machine-modeling of PM Synchronous motor                                   | YES |                |
| 37.   | Problem solved   | YES |                |
| 38.   | Revision of electromagnetic torque   | YES |                |
| 39.   | Revision of voltage equations  | YES |                |
| 40.   | Revision of synchronous machine inductance   | YES |                |
| 41.   | Problems on voltage equations(revision)  | YES |                |
| <b>UNIT V DYNAMIC ANALYSIS OF SYNCHRONOUS MACHINE</b> |  |     |                |
| 42.   | Dynamic performance of synchronous machine   | YES | [R1],[R2]      |
| 43.   | three -phase fault, comparison of actual and approximate transient torque characteristics                        | YES |                |
| 44.   | Equal area criteria, Problems on three phase fault, Revision of area criteria                                    | YES |                |
| 45.   | Revision of dynamic performance of synchronous machine   | YES |                |

## Teaching Strategies

The teaching in this course aims at establishing a good fundamental understanding of the areas covered using:

- Formal face-to-face lectures
- Tutorials, which allow for exercises in problem solving and allow time for students to resolve problems in understanding of lecture material.
- Laboratory sessions, which support the formal lecture material and also provide the student with practical construction, measurement and debugging skills.
- Small periodic quizzes, to enable you to assess your understanding of the concepts.

## Evaluation Strategies

|                    |   |     |
|--------------------|---|-----|
| Cycle Test – I     |   | 5%  |
| Cycle Test – II    | - | 5%  |
| Model Test         | - | 10% |
| Attendance         | - | 5%  |
| Seminar&Assignment | - | 5%  |
| Final exam         | - | 70% |

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**Prepared by:** Mrs.Anitha Sampath kumar

**Dated :**

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**Addendum**

**ABET Outcomes expected of graduates of B.Tech / EEE / program by the time that they graduate:**

- a) An ability to apply knowledge of mathematics, science, and engineering fundamentals.
- b) An ability to identify, formulate, and solve engineering problems.
- c) An ability to design a system, component, or process to meet the desired needs within realistic constraints such as economic, environmental, social, political, ethical, health and safety, manufacturability, and sustainability.
- d) An ability to design and conduct experiments, as well as to analyze and interpret data.
- e) An ability to use the techniques, skills, and modern engineering tools necessary for engineering practice.
- f) An ability to apply reasoning informed by the knowledge of contemporary issues.
- g) An ability to broaden the education necessary to understand the impact of engineering solutions in a global, economic, environmental, and societal context.
- h) An ability to understand professional and ethical responsibility and apply them in engineering practices.
- i) An ability to function on multidisciplinary teams.
- j) An ability to communicate effectively with the engineering community and with society at large.
- k) An ability in understanding of the engineering and management principles and apply them in project and finance management as a leader and a member in a team.
- l) An ability to recognize the need for, and an ability to engage in life-long learning.

**Program Educational Objectives**

**PEO1: PREPARATION**

Electrical Engineering Graduates are in position with the knowledge of Basic Sciences in general and Electrical Engineering in particular so as to impart the necessary skill to analyze and synthesize electrical circuits, algorithms and complex apparatus.

**PEO2: CORE COMPETENCE**

Electrical Engineering Graduates have competence to provide technical knowledge, skill and also to identify, comprehend and solve problems in industry, research and academics related to power, information and electronics hardware.

**PEO3: PROFESSIONALISM**

Electrical Engineering Graduates are successfully work in various Industrial and Government organizations, both at the National and International level, with professional competence and ethical administrative acumen so as to be able to handle critical situations and meet deadlines.

**PEO4: SKILL**

Electrical Engineering Graduates have better opportunity to become a future researchers/ scientists with good communication skills so that they may be both good team-members and leaders with innovative ideas for a sustainable development.

**PEO5: ETHICS**

Electrical Engineering Graduates are framed to improve their technical and intellectual capabilities through life-long learning process with ethical feeling so as to become good teachers, either in a class or to juniors in industry.

| Course Teacher | Signature |
|----------------|-----------|
| S. Dinakar Raj |           |

**Course Coordinator**  
(Mrs.Anitha Sampath  
kumar)

**HOD/EEE**

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